

Twist clamp cylinder——ACK Series

Compendium of ACK Series



Theoretical clamping force

Unit: Newton(N)

Bore size	Rod size		Operating pressure(MPa)												
(mm)	(mm)	0.1	0.2	0.3	0.4	0.5	0.6	0.7							
25	14	-	67.4	101.1	134.8	168.5	202.2	235.9							
32	16	60.3	120.6	181.0	241.3	301.6	361.9	422.2							
40	16	105.6	211.1	316.7	422.2	527.8	633.3	738.9							
50	20	164.9	329.9	494.8	659.7	824.7	989.6	1154.5							
63	20	280.3	560.6	840.9	1121.2	1401.5	1681.9	1962.2							

Installation and application

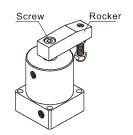


- 1. Clamping operation must be carried out within the clamping stroke and can not be performed within the swivel stroke.
- 2. Clamping plane must be vertical to the cylinder axes. After the components are clamped, don't move the components.
- 3. Before the cylinder is connected to pipeline, sundries in the pipe must be eliminated to prevent impurities entering the cylinder.
- 4. The medium used by cylinder shall be filtered to 40 $\mu\,m$ or below.
- 5. If the cylinder is dismantled and stored for a long time, please conduct anti-rust treatment to the surface. Anti-dust cap shall be added in inlet and outlet ports. The end of piston shall be coated with anti-rust oil.

Rocking shaft initial point adjustment

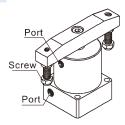
According to the actual need, loosening screw, may adjust the rocking shaft initial point.

Note: When assemble or disassemble the rocker by spanner and allen wrench; don't hold the body to assemble or disassemble rocker, it may damage the cylinder.



How to select the fitting for body's port

When ACK series with 180° rotation or ACKD is selected, miniature air fittings should be used to minimise obstruction.







ACK Series



Symbol



Product feature

- The material of seals guarantees the reliable performance of the cylinder that is used under various conditions.
- 2. Three-slot guide structure leads to high guide precision.
- There are single and double side clamping fingers can be selected (90°).
- 4. Levorotatory and dextrorotary are available; $90^{\circ} and \ 180^{\circ}.$
- 5. The material of piston rod is made from special alloy steel, which has longer life after heat treatment.

Specification

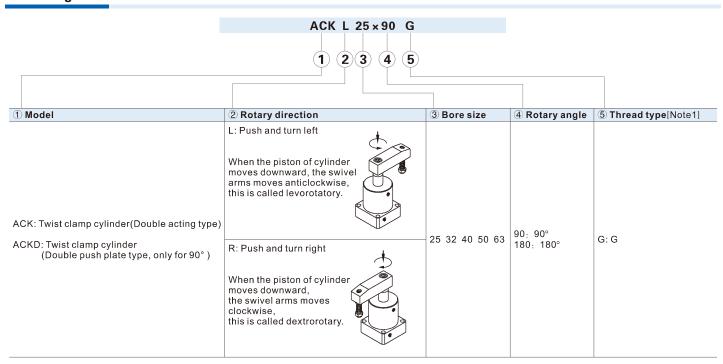
Bore size(mm)	25	32	40	50	63					
Acting type	Double acting									
Fluid	Air(to be filtered by 40 µ m filter element)									
Operating pressure	0.15~1.0MPa(22~145psi)									
Proof pressure	1.5MPa(215psi)									
Temperature °C	-20~70									
Speed range mm/s	50~200									
Stroke tolerance	+1.0									
Rotary angle tolerance	± 1.5°									
Cushion type [Note1]	No cushion									
Port size [Note2]	M5 × 0.8 1/8"									

[Note1] If there is no buffering device, exhaust throttle shall be added to achieve buffering effect.
[Note2] G thread is available.

Stroke

Bore size(mm)	Stroke type	90°	180°	Total stroke (90° /180°)					
25	Rotation stroke	14	20	26					
32	Clamping stroke	12	6	26					
40	Rotation stroke	15	21	27					
40	Clamping stroke	12	6	27					
50	Rotation stroke	15	21	29					
63	Clamping stroke	14	8	29					

Ordering code



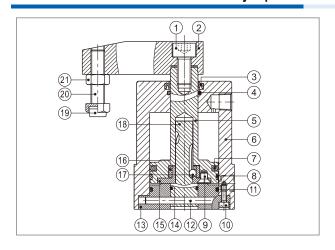
[Note1] When the thread is standard, the code is blank.





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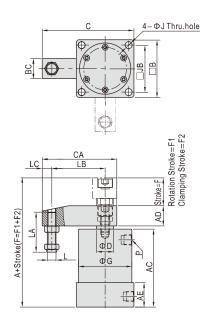
$Inner \, structure \, and \, material \, of \, major \, parts$



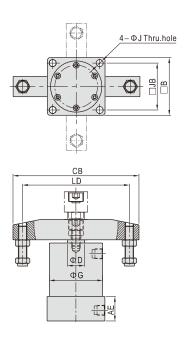
NO.	Item	Material	NO.	Item	Material				
1	Screw	Carbon steel	12	Fixed pin	S45C				
2	Rocker	Carbon steel	13	Back cover	Aluminum alloy				
3	Rod packing	NBR	14	O-ring	NBR				
4	O-ring	NBR	15	Push block	SCr440				
5	Piston rod	S45C	16	Bushing	SCr440				
6	Body	Aluminum alloy	17	Steel ball	Carbon steel				
7	Piston seal	NBR	18	Rotary axis	SCr440				
8	Wear ring	Wear resistant material	19	Bumper	PTFE				
9	Screw	Carbon steel	20	Screw	Carbon steel				
10	Screw	Carbon steel	21	Nut	Carbon steel				
11	O-ring	NBR							

Dimensions

ACK



ACKD



Bore size\Item	Α	AC	AD	ΑE	В	вс	С	CA	СВ	D	F(90° /180°)	F1(90°)	F1(180°	F2(90°)	F2(180°)	G	J	JB	L	LA	LB	LC	LD	Р
25	85	65	16	23	40	16	58	48	76	14	26	14	20	12	6	35	4.5	30	M6×1.0	29.5	30	8	60	M5×0.8
32	95	73	19	23	54	19	86	70	118	16	26	14	20	12	6	50	6.5	44	M8×1.25	37.5	50	9	100	1/8"
40	97	74	19	26	58	19	88	70	118	16	27	15	21	12	6	55	6.5	48	M8×1.25	37.5	50	9	100	1/8"
50	109.5	80	25.5	26	68	25.5	114	93	160	20	29	15	21	14	8	60	8.5	55	M10×1.5	45	70	10	140	1/8"
63	115.5	86	25.5	30	82	25.5	121	93	160	20	29	15	21	14	8	70	8.5	64	M10×1.5	45	70	10	140	1/8"

Twist clamp cylinder

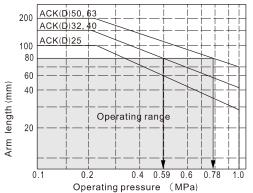


ACK Series

How to select product

- 1. When arms are to be made separately, their length and weight should be within the following range.
- 2. Allowable bending moment:

Use the arm length and operating pressure within graph(1) for allowablebending moment loaded piston rod.

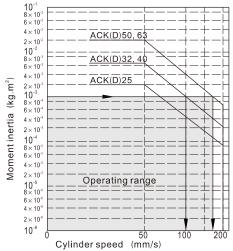


Example: When arm length is 80mm, pressure should be less than

ACK32/40:0.59MPa ACK50/63:0.78MPa

3. Moment of inertia:

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within graph(2) based on arm requirments.



Example: When arm's moment of inertia is $10^{-9} \text{Kg} \cdot \text{m}^2$, cylinder speed should be less than

ACK32/40:100mm/s

ACK50/63:170mm/s
Note) The average speed of piston=the highest speed of piston/1.6

4. Moment of inertia of cylinder's arm when rotating based on its rotary axis, shown in graph(3).

Model	Moment of inertia(Kg·m²)
ACK25 with single arm	2.006×10^{-5}
ACK25 with double arms	7.651×10^{-5}
ACK32\40 with single arm	1.271×10 ⁻⁴
ACK32\40 with double arms	4.148×10 ⁻⁴
ACK50\63 with single arm	9.614×10 ⁻⁴
ACK50\63 with double arms	1.888×10^{-3}

- 5. Calculation reference:
 - 5.1)Moment of inertia of arm (I1): Refer to the graph(3) after the cylinder bore diameter is determined.
 - 5.2)Moment of inertia of jig (I2): According to shape of the jig and the next item 6 "Calculation for moment of inertia", pick out a proper formula for calculation. The jig shown on the right graph is a cylinder, its formula of moment of inertia is: I,=(m,*D*D)/8+m,*L*L

When ACK32 is selected: L=0.05m(arm length); $\frac{\text{Jig mass} \cdot m_2}{\text{If D}=0.04\text{m}}$ $\frac{\text{m}_2=0.4\text{kg}}{\text{m}_2=0.4\text{kg}}$

From graph(3): I_1 =1.271×10⁻⁴(Kg·m²) By Calculation : I_2 =(m_2 *D*D)/8+ m_2 *L*L= (0.4*0.04*0.04)/8+0.4*0.05*0.05 =10.8×10⁻⁴(Kg·m²)

Total value: $I = I_1 + I_2 = 12.071 \times 10^{-4} = 1.2071 \times 10^{-3} (\text{Kg} \cdot \text{m}^2)$

According to graph(2), the highest speed of the cylinder should be less than 95 mm/s; According to graph(1), it can be used under a pressure of 0.9Mpa. The average speed of piston=the highest speed of piston/1.6=59 mm/s.

jig: I

6 Calculation for moment of inertia

Diagram	Calculation formula of moment of inertia
1. Thin bar Position of rotary axis: Vertical to the bar and through the end	$1 = \frac{m_1 a_1^2 + m_2 a_2^2}{3}$
Position of rotary axis: /ertical to the bar and hrough the center of gravity	I=\frac{ma^2}{12}
3. Load at the end of lever arm a_2 m_2	$I = m_{1} \times \frac{a_{1}^{2}}{3} + m_{2} \times a_{2}^{2} + k$ $k = m_{2} \times \frac{2r^{2}}{5}$
4. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Parallel to side b and through the center of gravity	$I = \frac{ma^2}{12}$
5. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Vertica to the plate and through the end	$I = m_1 \times \frac{4a_1^2 + b^2}{12} + m_2 \times \frac{4a_2^2 + b^2}{12}$
6. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Through the center of gravity and vertical to the plate(Same as	$I = \frac{ma^2 + mb^2}{12}$

also thickrectanglaur plate)